

CENTAURO Robots and Exoskeleton:

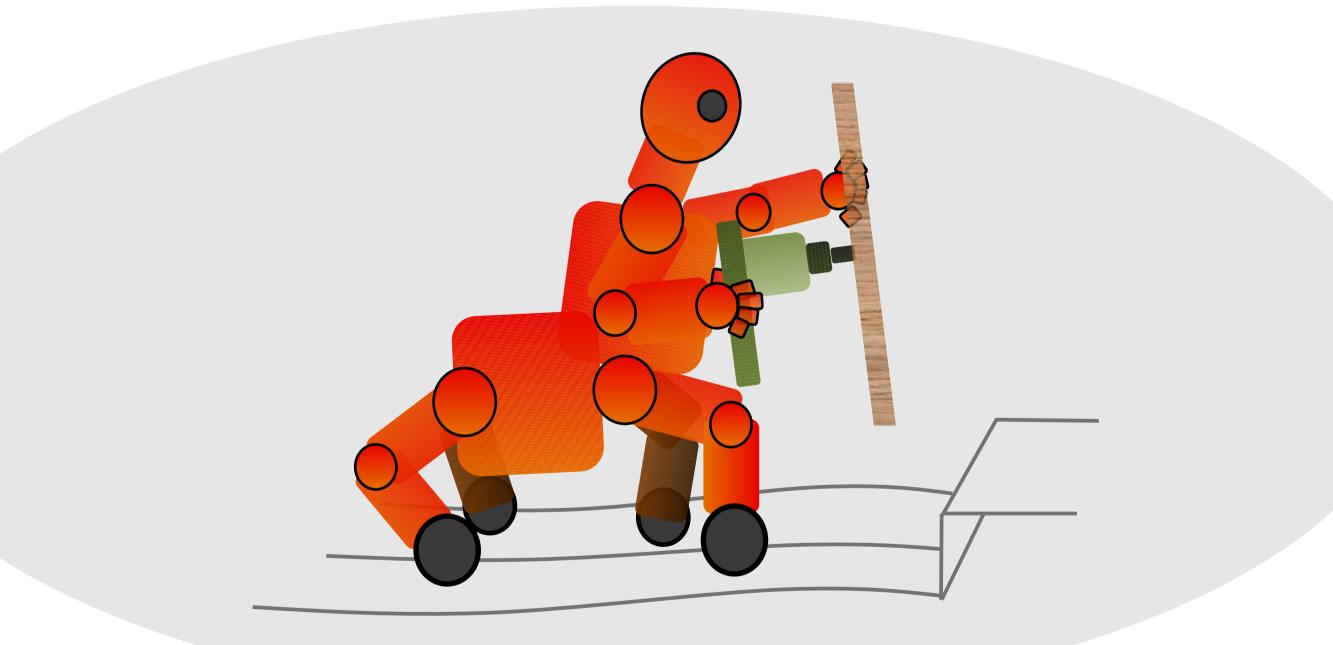


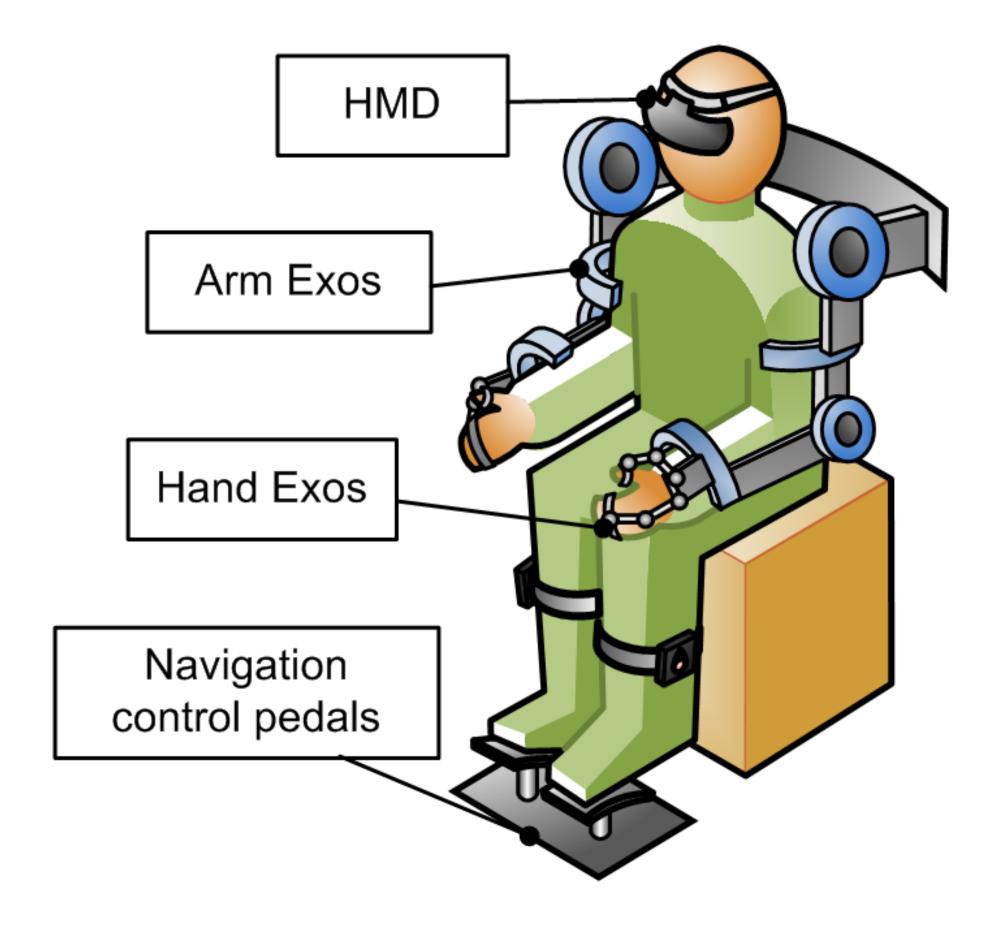
Realistic high-resolution render image of a CENTAURO mock up model by RWTH Aachen in an urban disaster scenario.



Mobile manipulation robot Momaro

(by University of Bonn) has been specifically designed to the requirements of the DARPA Robotics Challenge.





Schematic visualisation of CENTAURO robot

performing desaster response task.

The operator interface with:

- Head Mounted Display (HMD)
- Anthropomorphic upper body exosceleton (arm, shoulder)
- Anthropomorphic hand exosceleton
- Navigation controlpanels